

#sample code for testing the continuous servo motor MG995 with the rack and pinion

```
import time
from adafruit_crickit import crickit

print("Servo motor running...")

# Run servo forward
crickit.continuous_servo_1.throttle = 0.7
time.sleep(2)

# Stop servo
crickit.continuous_servo_1.throttle = 0
time.sleep(1)

# Run servo in reverse
crickit.continuous_servo_1.throttle = -0.7
time.sleep(2)

# Stop servo finally
crickit.continuous_servo_1.throttle = 0
print("Servo stopped")
```